

ISE789

Sampling

19 October 2010

Paper

- Monte Carlo (Importance) Sampling Within Benders Decomposition Algorithm for Stochastic Linear Programs
- By Gerd Infanger
- Annals of Operations Research 39 (1992)

Outline

- Introduction
- Crude Monte Carlo
- Importance Sampling
- Importance Sampling in Benders
- Bounds (Clay and Omar)
 - Upper and Lower Bounds
 - Stopping
 - Confidence Bounds

Assumptions

- 2-Stage stochastic program
- Fixed recourse
- 2nd stage cost coefficients are deterministic
- Components of ξ or V are independent.

Introduction

- Main idea of importance sampling
 - Reduce time to achieve desired accuracy
- Need to sample if distribution of ξ is continuous or large and discrete
- Individual components of ξ don't have to have large discrete support if dimension is even modestly sized

Example

- ξ is 15-dimensional and each component is independent and uniformly distributed over the integers 1,2,...,10.
- How many scenarios are required to obtain universe solution?
- Why might this be a problem?
 - (say it takes 1 second to solve each LP...)

Crude Monte Carlo

$$z = \sum_{\omega \in \Omega} C(v^{\omega}) p(v^{\omega})$$

3.1. CRUDE MONTE CARLO

Suppose v^{ω} , $\omega = 1, \dots, n$ are scenarios, sampled independently from their joint probability mass function, then $C^{\omega} = C(v^{\omega})$ are independent random variates with expectation z .

$$\bar{z} = (1/n) \sum_{\omega=1}^n C^{\omega} \tag{6}$$

is an unbiased estimator of z and its variance is

$$\sigma_{\bar{z}}^2 = \sigma^2 / n,$$

$$\sigma^2 = \text{var}(C(V)).$$

Thus, the standard error is decreasing with sample size n by $n^{-0.5}$. The convergence rate of \bar{z} to z is independent of the dimension h of the random vector V .

Importance Sampling

- Reduce the variance of \bar{z}
 - Could just increase sample size
- Introduce a new probability mass function that gives greater weight to some scenarios

$$z = \sum_{\omega \in \Omega} C(v^\omega) p(v^\omega) = \sum_{\omega \in \Omega} \frac{C(v^\omega) p(v^\omega) q(v^\omega)}{q(v^\omega)}$$

$$\bar{z} = \frac{1}{n} \sum_{\omega=1}^n \frac{C(w^\omega) p(w^\omega)}{q(w^\omega)},$$

Intuitively...

- We want to sample scenarios which contribute most to the expectation
- Scenarios with high value
- Scenarios with high mass (pmf)
- Ideally, both!

How to choose q ?

$$\text{var}(\bar{z}) = \frac{1}{n} \sum_{\omega \in \Omega} \left(\frac{C(w^\omega) p(w^\omega)}{q(w^\omega)} - z \right)^2 q(w^\omega).$$

- The perfect q requires what we are measuring

$$q^*(w^\omega) = \frac{C(w^\omega) p(w^\omega)}{\sum_{\omega \in \Omega} C(w^\omega) p(w^\omega)}$$

- Try to approximate the perfect q
 - Penalty for bad approximation is just higher sample size

How to choose q ?

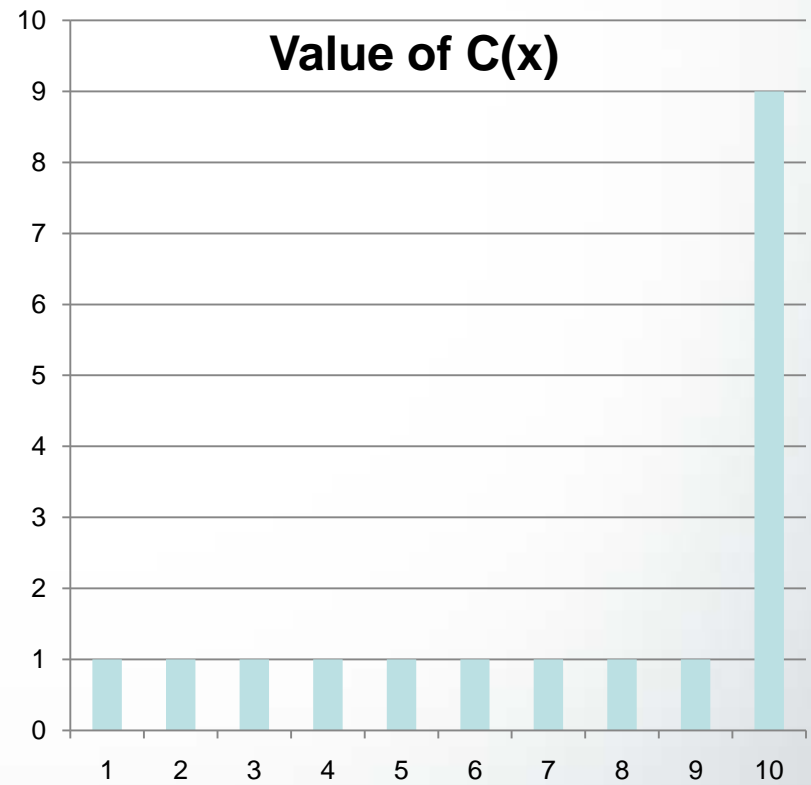
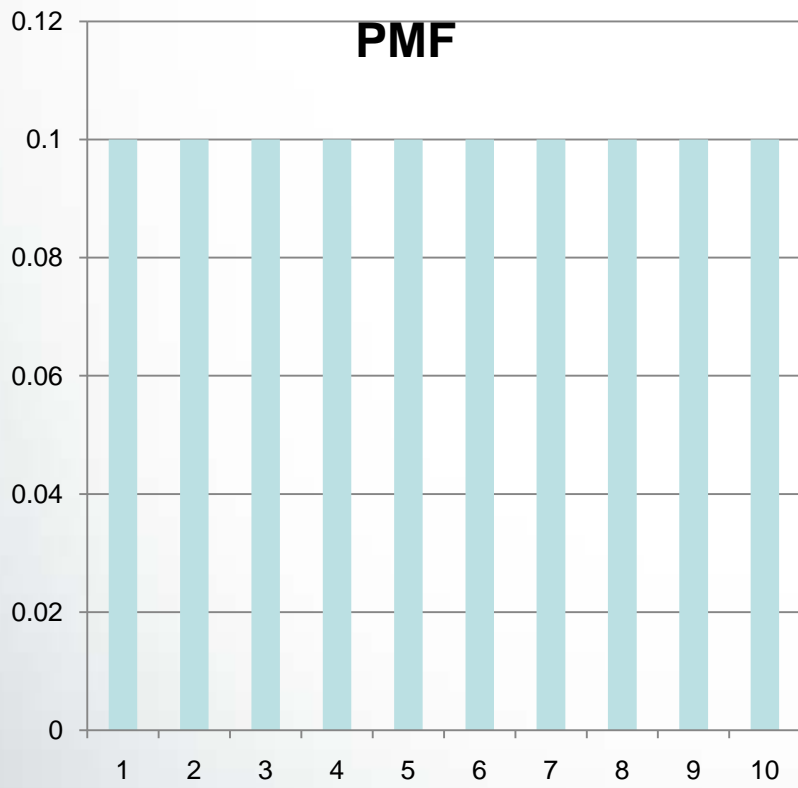
- Additivity reduces number of scenarios by isolating each component of ξ
 - No combinatorial explosion

$$C(V) \approx \sum_{i=1}^h C_i(V_i)$$

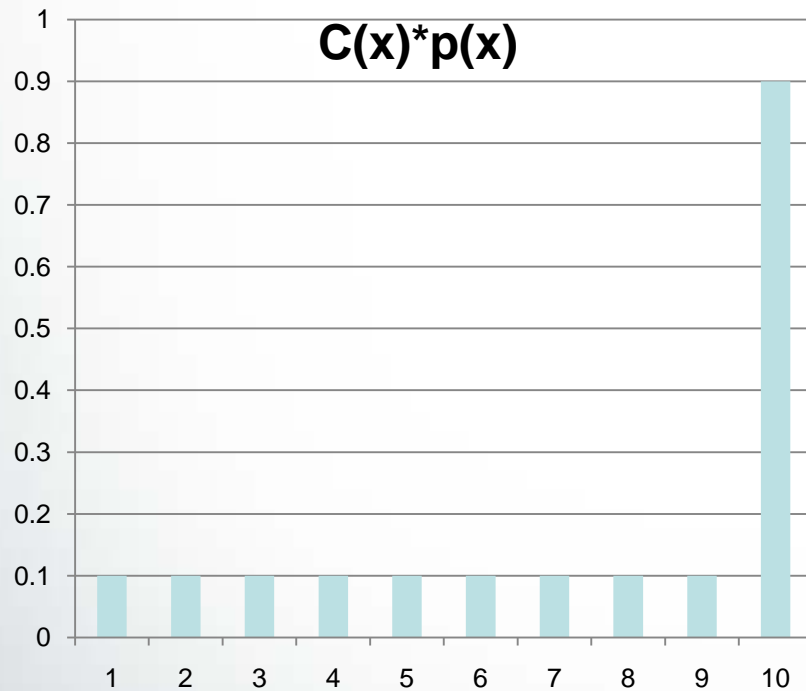
$$q(w^\omega) \approx \frac{C(w^\omega)p(w^\omega)}{\sum_{i=1}^h \sum_{\omega \in \Omega} C_i(w^\omega)}.$$

Example:

Expectation of a random variable



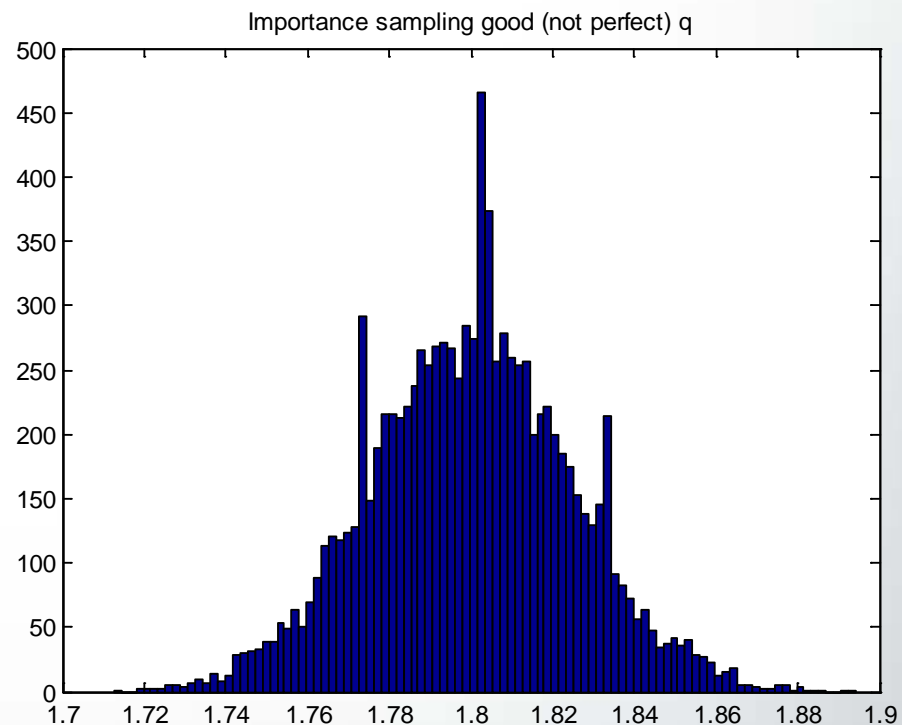
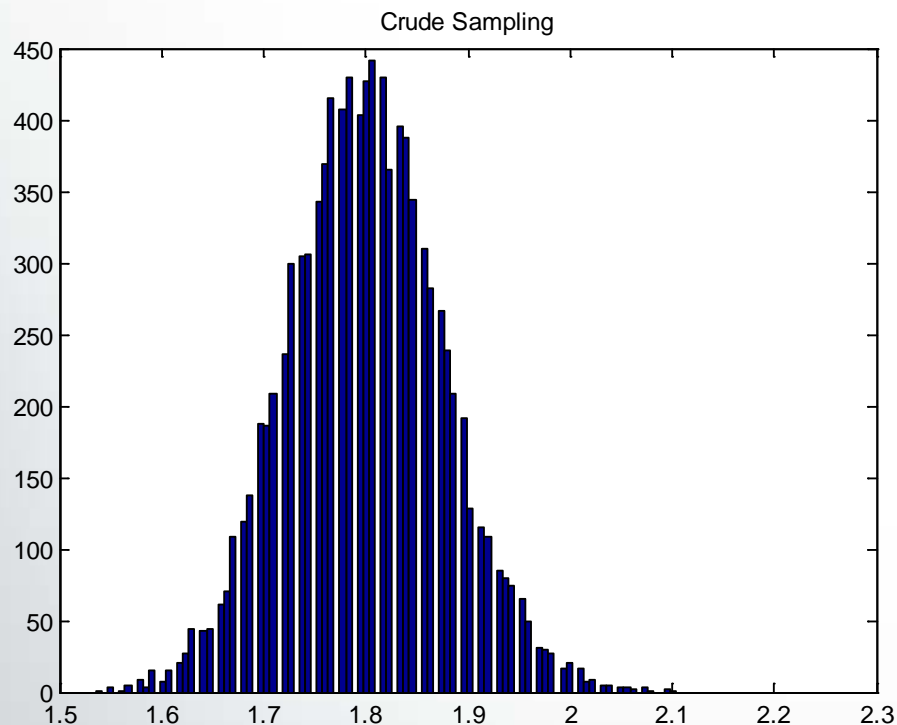
Importance of each scenario



- Can you calculate q^* ?
 - Try it

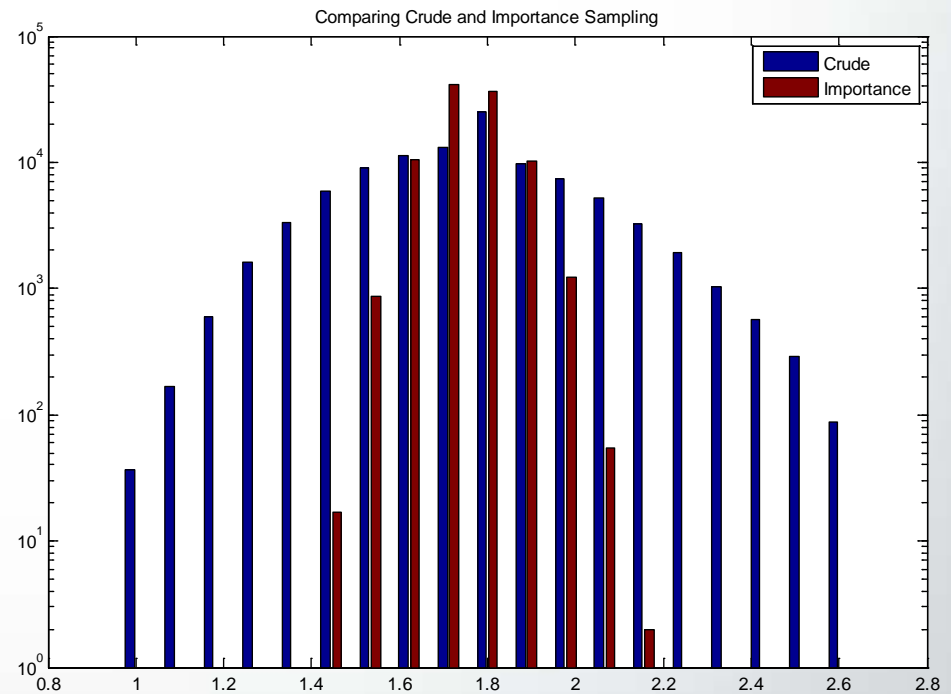
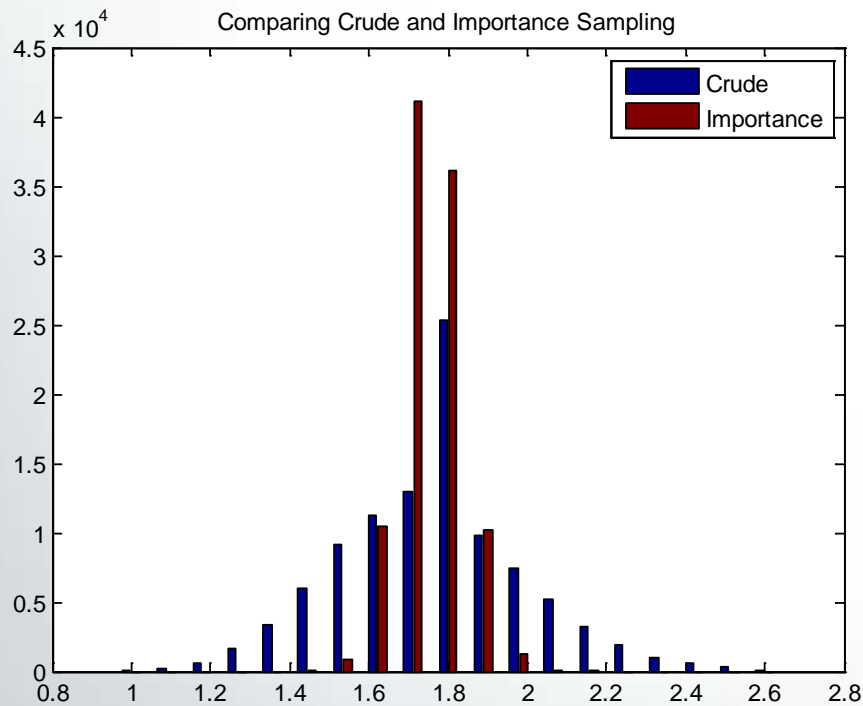
Matlab Example

(1,000 points and 10,000 batches)



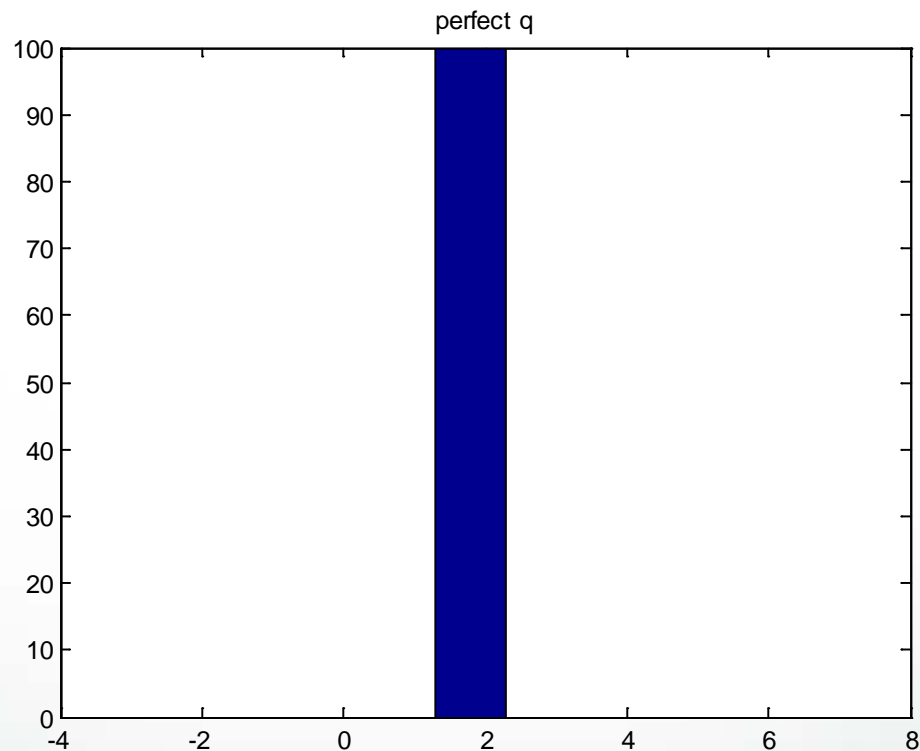
Matlab Example

(1,00 points and 10,0000 batches)

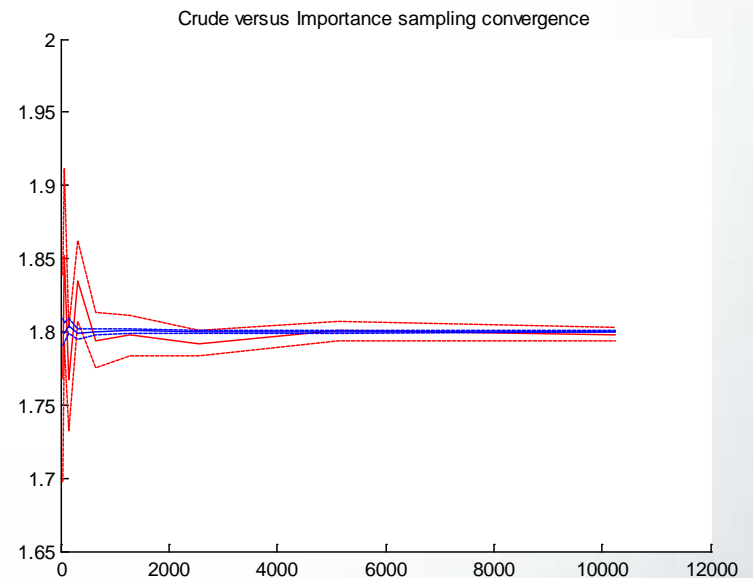
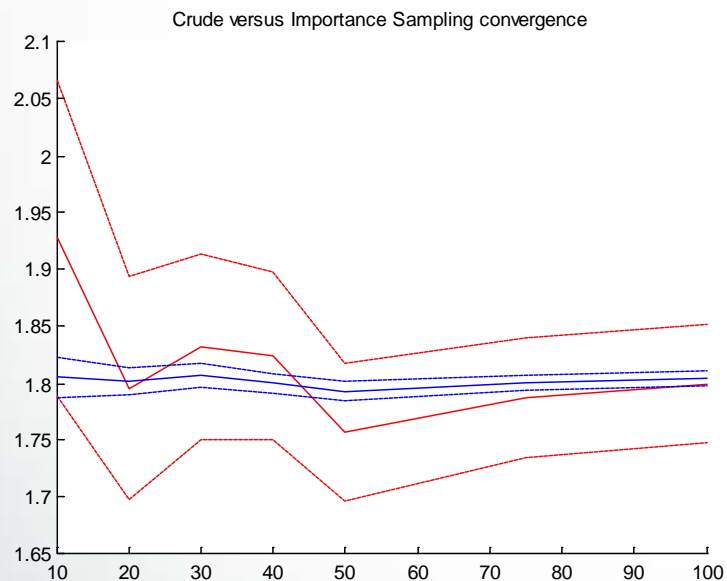


Matlab Example

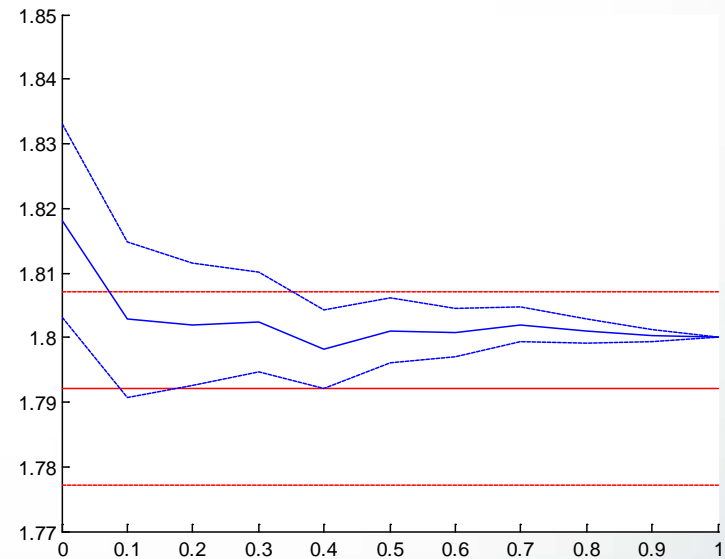
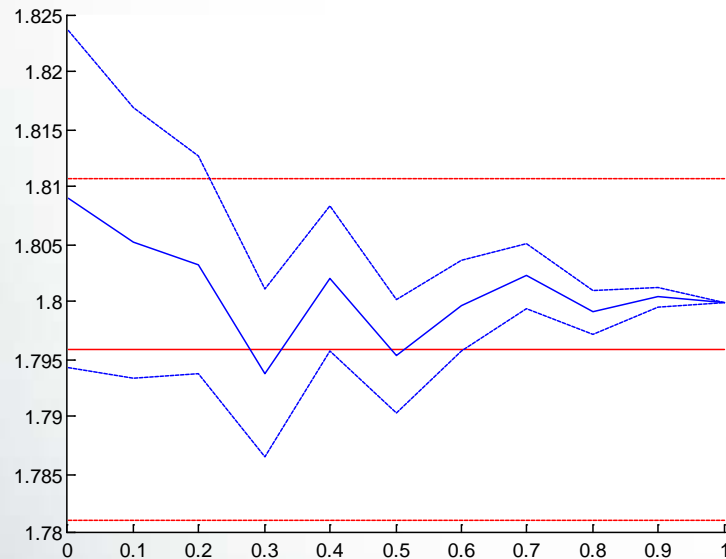
(100 points and 100 batches)



Convergence comparison



Importance of “good” q



How to choose q in practice?

- Entriken and Nakayama approach
 - Get huge reduction in variance for one experiment over Crude Monte Carlo
 - Via additive approximation and independence, we construct a base case
 - Then from the base case we can construct marginal cost functions
 - Then from those we can find weights (q values) which we sample from

$$C(V, \hat{X}) \approx \Gamma(V, \hat{X}) = C(\tau, \hat{X}) + \sum_{i=1}^h M_i(V_i, \hat{X}), \quad (7)$$

$$M_i(V_i, \hat{X}) = C(\tau_1, \dots, \tau_{i-1}, V_i, \tau_{i+1}, \dots, \tau_h, \hat{X}) - C(\tau, \hat{X}).$$

$$\bar{M}_i(\hat{X}) = E M_i(V_i, \hat{X}) = \sum_{\omega \in \Omega_i} M_i(v_i^\omega, \hat{X}) p(v_i^\omega) \quad (8)$$

$$F(v^\omega, \hat{X}) = \frac{C(v^\omega, \hat{X}) - C(\tau, \hat{X})}{\sum_{i=1}^h M_i(v_i^\omega, \hat{X})} \quad (9)$$

$$z(\hat{X}) = C(\tau, \hat{X}) + \sum_{i=1}^h \bar{M}_i(\hat{X}) \sum_{\omega \in \Omega} F(v^\omega, \hat{X}) \frac{M_i(v_i^\omega, \hat{X})}{\bar{M}_i(\hat{X})} \prod_{j=1}^h p_j(v_j^\omega). \quad (10)$$

B and L example, pgs 338-9

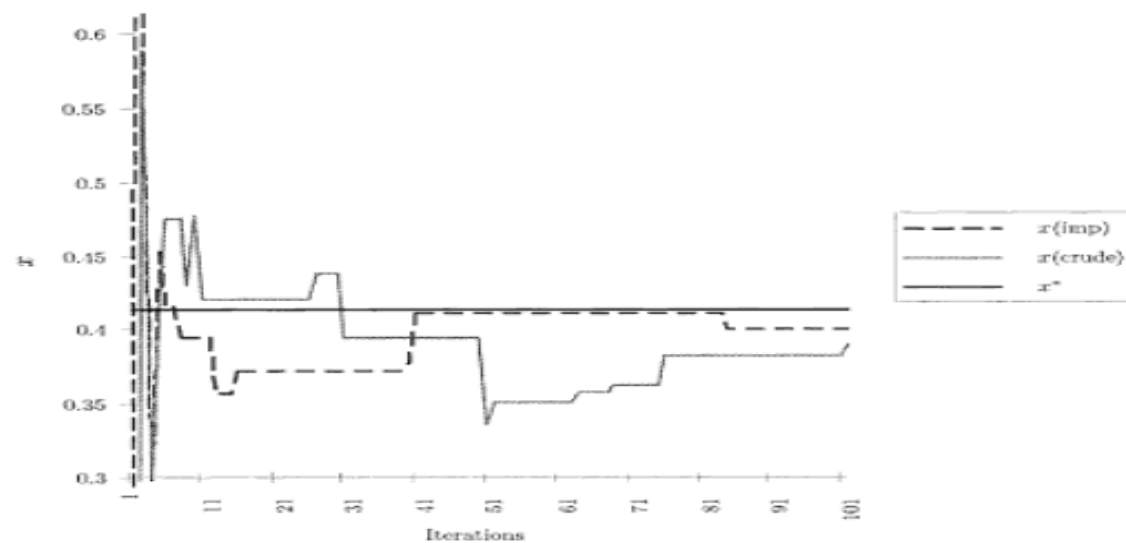


FIGURE 1. Solutions for crude Monte Carlo and importance sampling.

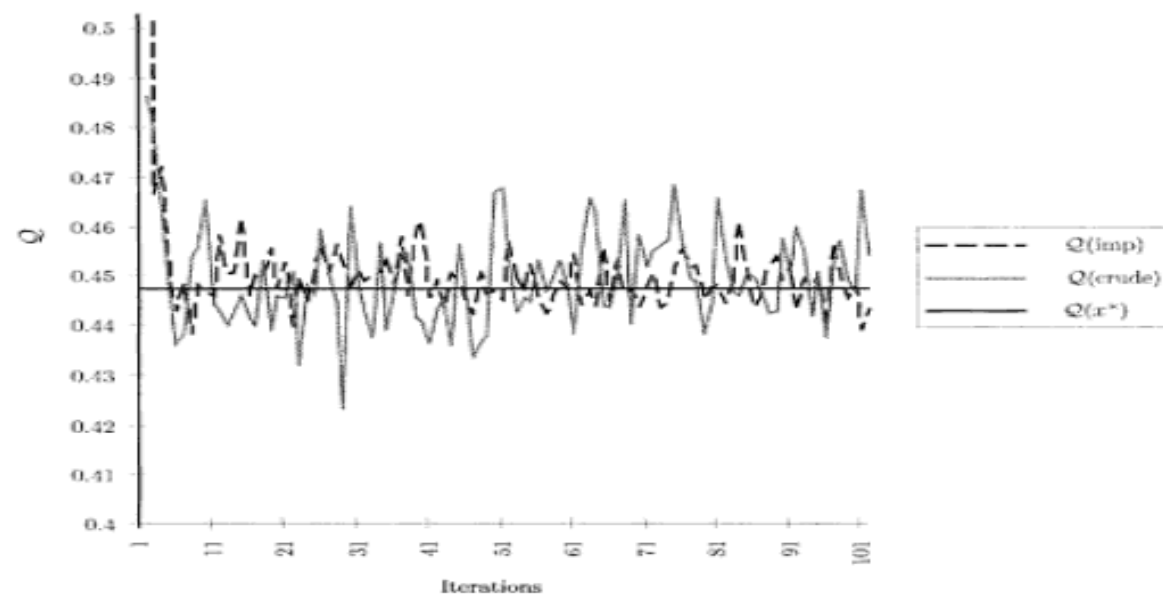


FIGURE 2. Objective values for crude Monte Carlo and importance sampling.

Other Good References on IS specifically

- Notes by Eric C Anderson
 - http://ib.berkeley.edu/labs/slatkin/eriq/classes/guest_lect/mc_lecture_notes.pdf
- P H Borchers
 - <http://iopscience.iop.org/0143-0807/21/5/305/pdf/ej0505.pdf>

Other Good References on IS in SP

- Our Book
- Shapiro paper
 - Mathematical Programming 81 (1998)